

Entropy stable reduced order modeling of nonlinear conservation laws using discontinuous Galerkin methods

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Abstract

- Extension of entropy stable reduced order models (ROMs) of nonlinear conservation laws from finite volume methods [1] to **high order discontinuous Galerkin (DG) methods**.
- Hyper-reduction techniques: **gappy proper orthogonal decomposition** (gappy-POD) and **Carathéodory pruning**.

Background

- Nonlinear conservation laws with conservative variables $\mathbf{u} \in \mathbb{R}^n$ on domain Ω

$$\frac{\partial \mathbf{u}}{\partial t} + \sum_{i=1}^d \frac{\partial \mathbf{f}_i(\mathbf{u})}{\partial \mathbf{x}_i} = 0, \quad (\mathbf{x}, t) \in \Omega \times [0, \infty). \quad (1)$$

- Many systems admit an entropy inequality with convex entropy function $S(\mathbf{u})$

$$\int_{\Omega} \frac{\partial S(\mathbf{u})}{\partial t} d\mathbf{x} + \sum_{i=1}^d \int_{\partial \Omega} (\mathbf{v}^T \mathbf{f}_i(\mathbf{u}) - \psi_i(\mathbf{u})) \mathbf{n}^i \leq 0. \quad (2)$$

- **Entropy stability** is a generalization of energy stability.

Reduced order modeling

- The global DG formulation of (1) is

$$\mathbf{M} \frac{d\mathbf{u}}{dt} + \sum_{i=1}^d (2\mathbf{Q}^i \circ \mathbf{F}^i) \mathbf{1} + \mathbf{B}^i \mathbf{f}^{i,*} = \mathbf{0}, \quad (3)$$

where $(\mathbf{F}^i)_{j,k} = \mathbf{f}_i(\mathbf{u}_j, \mathbf{u}_k)$ is the entropy conservative flux, \mathbf{Q}^i is a **summation by parts (SBP) operator** with $\mathbf{Q}^i \mathbf{1} = \mathbf{0}$.

- Galerkin projection ROM (\mathbf{V}_N is the **POD basis**):

$$\mathbf{M}_N \frac{d\mathbf{u}_N}{dt} + \sum_{i=1}^d (2\mathbf{V}_N^T \mathbf{Q}^i \circ \mathbf{F}^i) \mathbf{1} + \mathbf{V}_b^T \mathbf{B}^i \mathbf{f}^{i,*} = \mathbf{0}, \quad (4)$$

$\mathbf{u} \approx \mathbf{V}_N \mathbf{u}_N$ and \mathbf{V}_b is a boundary submatrix of \mathbf{V}_N .

- Due to nonlinear terms, the cost of (4) still scales with the dimension of the FOM. We will construct a **hyper-reduced ROM** from hyper-reduced operators $\bar{\mathbf{V}}_N, \bar{\mathbf{Q}}^i, \bar{\mathbf{V}}_b,$ and $\bar{\mathbf{B}}^i$:

$$\bar{\mathbf{M}}_N \frac{d\mathbf{u}_N}{dt} + \sum_{i=1}^d (\bar{\mathbf{V}}_N^T ((\bar{\mathbf{Q}}^i - \bar{\mathbf{Q}}^{i,T}) \circ \mathbf{F}^i) \mathbf{1} + \bar{\mathbf{V}}_b^T \bar{\mathbf{B}}^i \mathbf{f}^{i,*}) = \mathbf{0}.$$

Hyper-reduction of volume terms

First, we utilize a greedy algorithm [3] to construct hyper-reduced indices I and weights \mathbf{w} for a target space

$$\mathbf{V}_{\text{target}}^T \mathbf{w}_{\text{target}} \approx \mathbf{V}_{\text{target}}(I, :)^T \mathbf{w}, \quad \mathbf{w}_{\text{target}}, \mathbf{w} > 0, \quad \bar{\mathbf{M}}_N = \mathbf{V}_N(I, :)^T \text{diag}(\mathbf{w}) \mathbf{V}_N(I, :). \quad (5)$$

Then, we use a two-step "compress and project" procedure to build $\bar{\mathbf{Q}}^i$, starting with a test basis \mathbf{V}_t^i such that $\mathbf{1}, \mathbf{V}_N$, and $\mathbf{Q}^i \mathbf{V}_N$ are in its range

$$\bar{\mathbf{Q}}^i = (\mathbf{V}_t^i)^T \mathbf{Q}^i \mathbf{V}_t^i, \quad \bar{\mathbf{V}}_t^i = \mathbf{V}_t^i(I, :), \quad \bar{\mathbf{Q}}^i = ((\bar{\mathbf{V}}_t^i)^{\dagger})^T \bar{\mathbf{Q}}^i (\bar{\mathbf{V}}_t^i)^{\dagger} \quad (\text{gappy-POD}). \quad (6)$$

$\bar{\mathbf{Q}}^i$ is the **hybridized SBP differentiation operator** [2] along the i th coordinate

$$\bar{\mathbf{Q}}^i = \frac{1}{2} \begin{bmatrix} \bar{\mathbf{Q}}^i - (\bar{\mathbf{Q}}^i)^T & \bar{\mathbf{E}}_i^T \bar{\mathbf{B}}^i \\ -\bar{\mathbf{B}}^i \bar{\mathbf{E}}_i & \bar{\mathbf{B}}^i \end{bmatrix}. \quad (7)$$

Hyper-reduction of boundary terms using Carathéodory pruning

Define $\mathbf{E}^i = \mathbf{V}_{bt}^i \mathbf{P}_t^i$, where \mathbf{V}_{bt}^i is a boundary submatrix of \mathbf{V}_t^i and $\mathbf{B}^i = \text{diag}(\mathbf{n}^i) \text{diag}(\mathbf{w}_b)$. Our goal is to find hyper-reduced boundary matrix $\bar{\mathbf{B}}^i$ such that

$$\mathbf{1}^T \bar{\mathbf{B}}^i \bar{\mathbf{E}}^i = \mathbf{1}^T \mathbf{B}^i \mathbf{E}^i = \mathbf{1}^T \mathbf{Q}^i. \quad (8)$$

Carathéodory's Theorem states that, given any positive quadrature rule on a space V with $\dim(V) = N$, we can generate an N -point interpolatory positive rule that **preserves all moments**. Therefore, from

$$\mathbf{1}^T \mathbf{B}^i \mathbf{V}_{bt} = \int \phi_{t,j} \mathbf{n}^i = \sum_k \mathbf{w}_{b,j} \mathbf{n}_j^i \phi_{t,j}(\mathbf{x}_k), \quad (9)$$

we are able to select N boundary nodes I_b with new positive weights $\bar{\mathbf{w}}_b$ from it to construct

$$\bar{\mathbf{V}}_{bt}^i = \mathbf{V}_{bt}^i(I_b, :), \quad \bar{\mathbf{E}}_i = \bar{\mathbf{V}}_{bt}^i \mathbf{P}_t^i, \quad \bar{\mathbf{B}}^i = \text{diag}(\mathbf{n}^i) \text{diag}(\bar{\mathbf{w}}_b), \quad \mathbf{1}^T \bar{\mathbf{B}}^i \bar{\mathbf{E}}^i = \mathbf{1}^T \mathbf{B}^i \mathbf{E}^i. \quad (10)$$

Numerical experiments

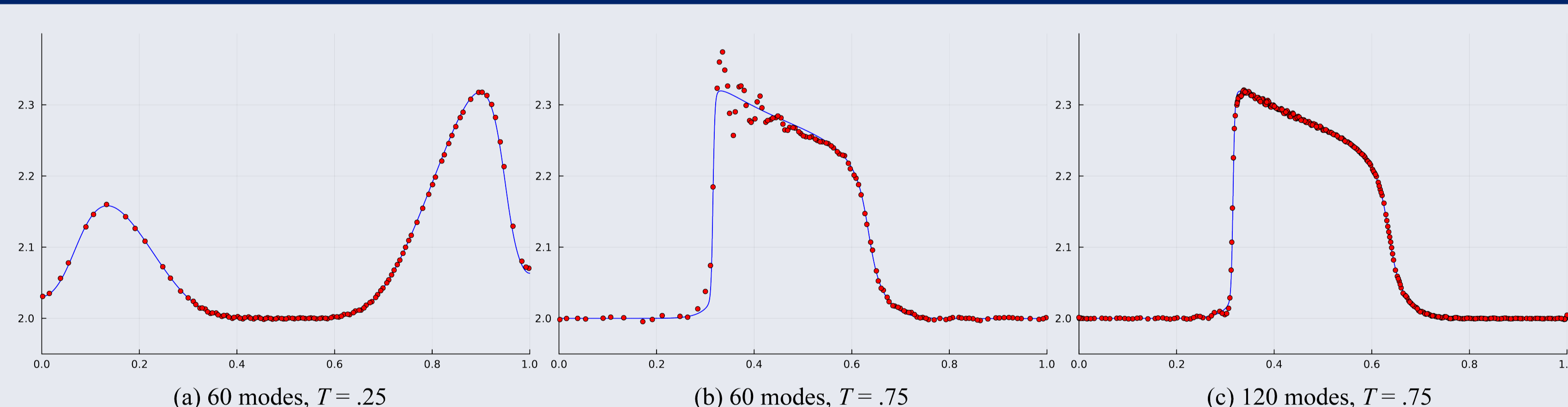


Figure: Density ρ . FOM solutions are displayed using line plots, while ROM solutions are indicated on hyper-reduced nodes in red.

1D compressible Euler equations with **reflective wall** boundary conditions, using a FOM with 256 elements, polynomial degree $N = 4$, and an artificial viscosity term $\epsilon \Delta \mathbf{u}$ with $\epsilon = 2e - 4$.

Numerical experiments

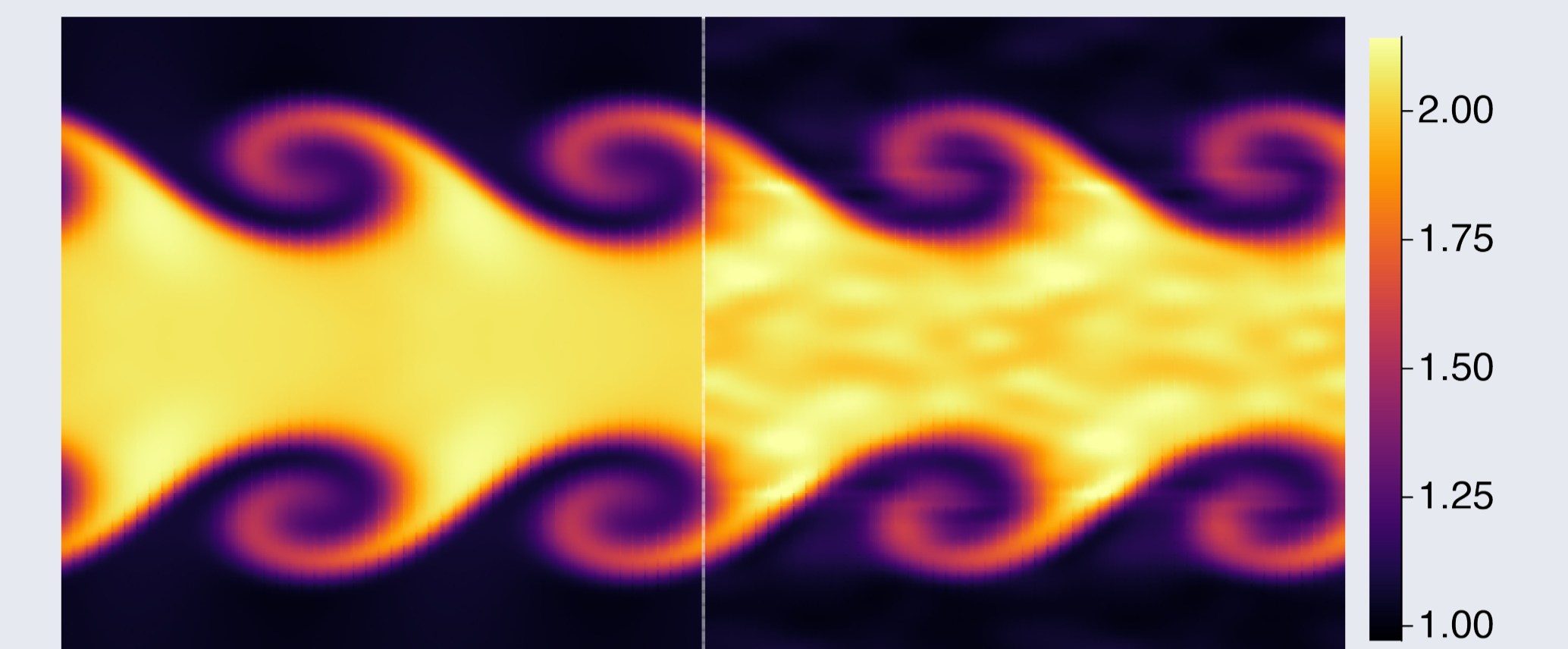


Figure: Density ρ at $T = 3.0$ in Kelvin-Helmholtz instability simulation: FOM (left) vs. ROM (125 modes, right).

- Smoothed Kelvin-Helmholtz instability: 2D compressible Euler equations on a **periodic** domain $[-1, 1]^2$ of 50×50 elements and polynomial degree $N = 4$.
- We add viscosity with $\epsilon = 1e - 3$, run the simulation until $T = 3.0$, and use 100 snapshots enriched with entropy variables for POD modes. We employ 125 modes for ROM, which remains **stable** despite under-resolution.

Conclusion and Acknowledgement

- We present an entropy stable reduced order modeling of nonlinear conservation laws based on high order DG methods.
 - We develop structure-preserving hyper-reduction techniques which preserve entropy stability.
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References

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